

# **Numerical Mathematics:**

## **Homework 2**

Due on T.B.D at 24:00pm

## Problem 1

Recall (from your linear algebra class) the singular value decomposition of a matrix  $A \in \mathbb{R}^{n \times n}$ :

$$A = U \Sigma V^T$$

where  $U, V \in \mathbb{R}^{n \times n}$  are orthogonal matrices, and

$$\Sigma = \begin{bmatrix} \sigma_1 & & & \\ & \sigma_2 & & \\ & & \ddots & \\ & & & \sigma_n \end{bmatrix}, \quad \sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_n > 0.$$

is a diagonal matrix. Find an expression of the condition number  $\|A\| \|A^{-1}\|$  in terms of the singular values. Also, what is the condition number of a unitary matrix? What does this mean from a computational standpoint?

## Problem 2

Make a function to solve a lower triangular system using forward substitution problem. Call this function `solve_lowertriangular.m`. It should take in two arguments: the first argument is a square matrix  $A$  and the second argument a vector  $b$ . The output should be  $x$ . Do the same for an upper triangular system. Call this function `solve_uppertriangular.m`.

Obviously, do not use the backslash operator (only can be used to checking purposes). For the output  $x$ , it is important to initialize an array of zeros first. Matlab allows one to dynamically extend the length of a vector dynamically, but this slows down the code.

Can you give a rough estimate of what the computational complexity is of this algorithm depending on problem size? Use big-O notation.

## Problem 3

Make a function that finds the LU factorization of a matrix  $A$ . Call this function `find_LU.m`. It should take as argument a matrix  $A$  and return two outputs: the first one should be  $L$  and the second one is  $U$ . If the algorithm encounters a zero pivot, make the function print a message. Obviously you should break the loop, because it makes no sense to continue after that.

## Problem 4

Use the code written in problem 1 and problem 2 to close the deal. Write a function called `solve_linearsystem.m` that solves a square linear system. It should take in two arguments: the first argument is a square matrix  $A$  and the second argument a vector  $b$ . The output should be  $x$ . You must call the functions you have made in problems 1 and 2 in your code.

## (extra) Problem 5

Repeat problems 3 and 4, but now add partial pivoting to it. Call the new functions `find_LUpartialpivot.m` and `solve_linearsystems_partialpivot.m` respectively. Note that there is NO NEED to explicitly construct a permutation matrix!